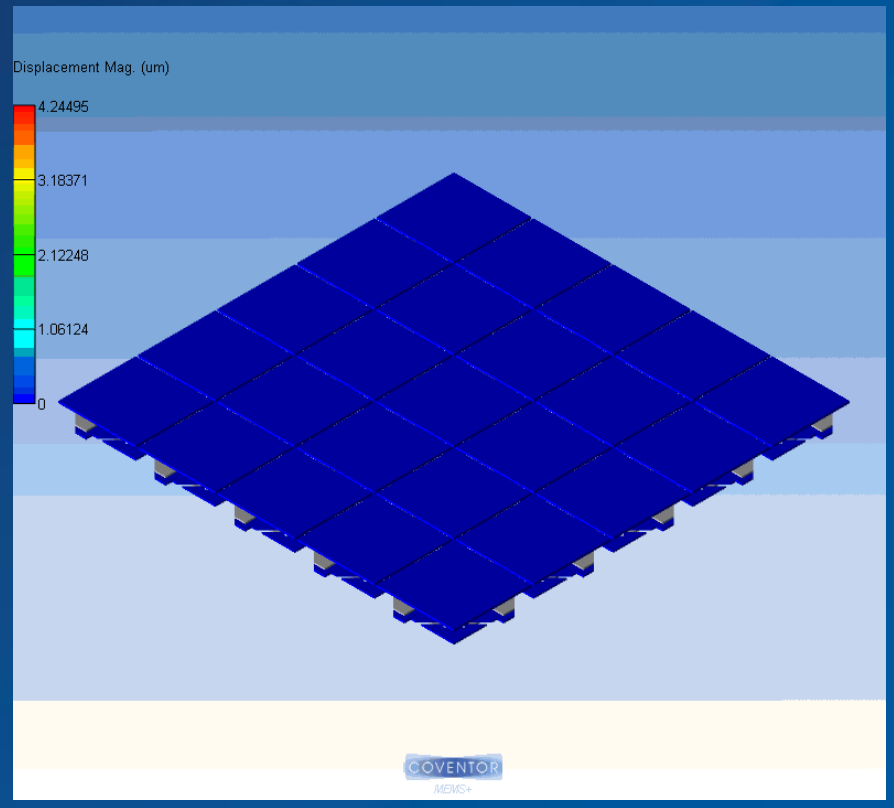
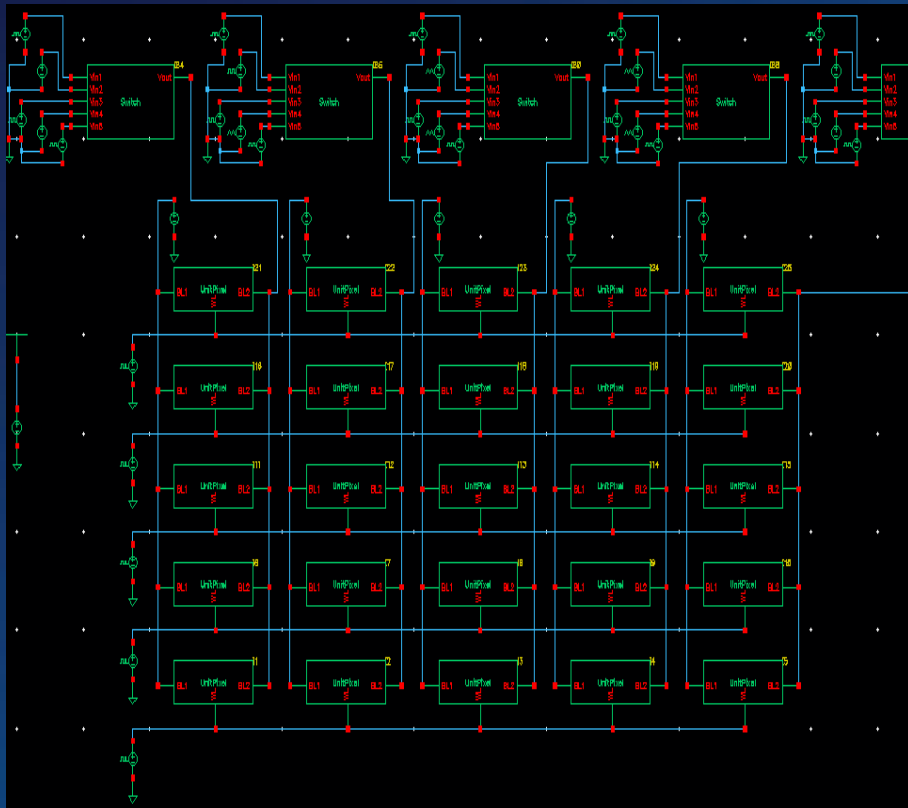


New paradigm for MEMS+IC Co-development



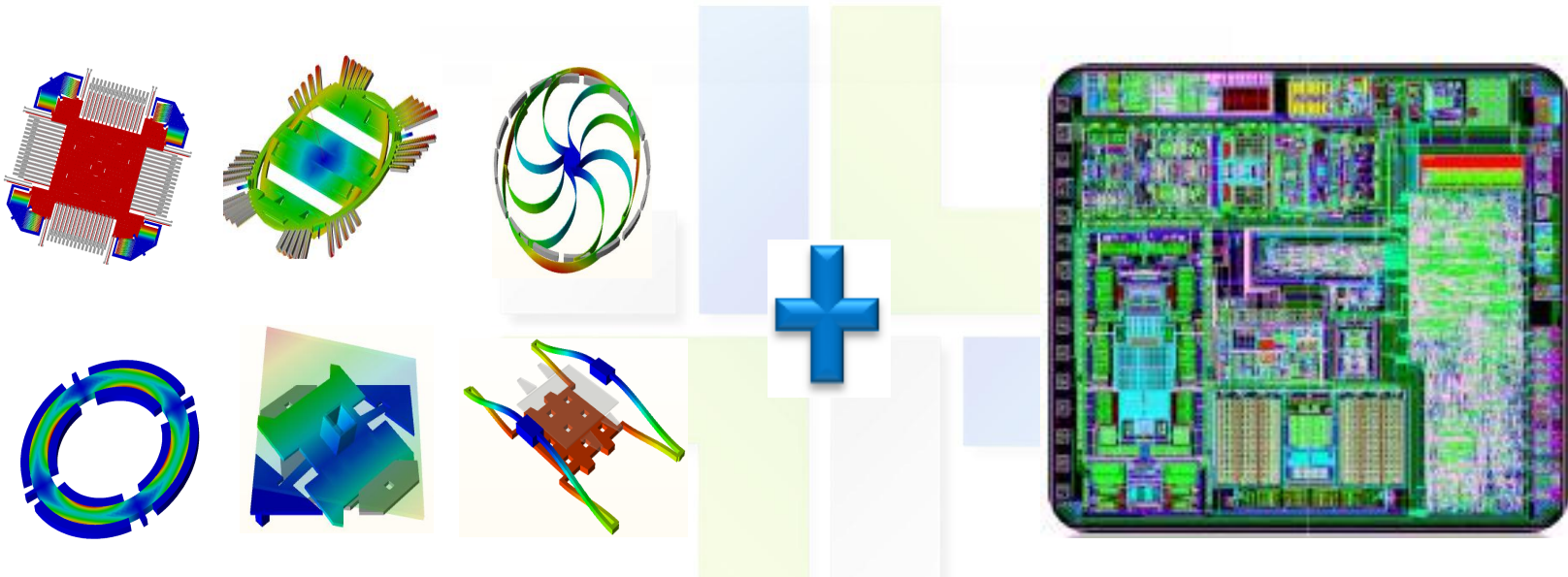
MEMS 진보된 스마트 세상을 만듭니다.



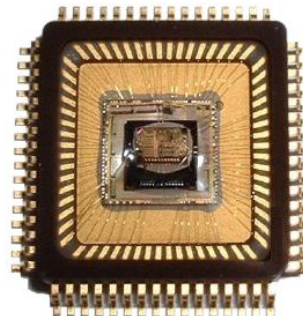
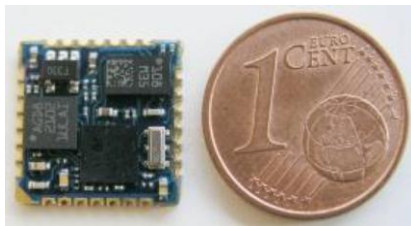
Smarter

Smaller Superior

New paradigm for MEMS+IC Co-development



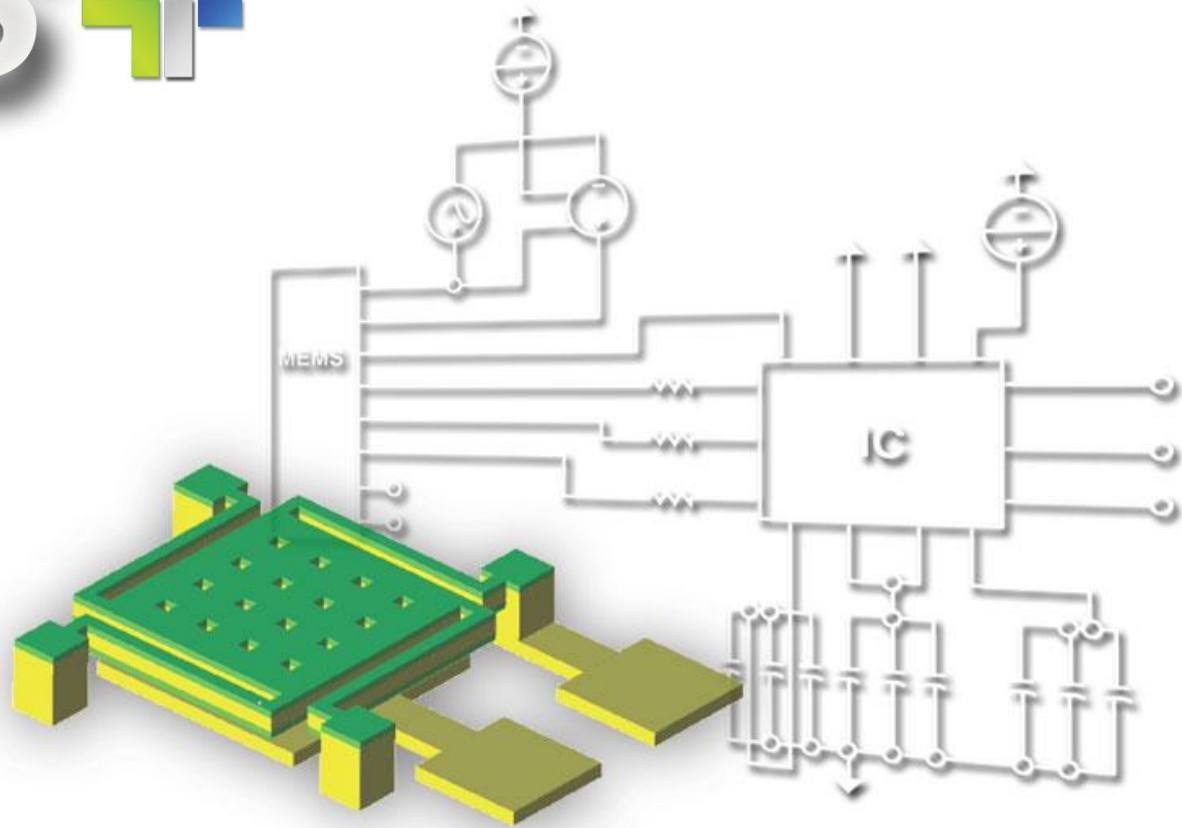
Worldwide First MEMS+IC Co-development Solution



New paradigm for MEMS+IC Co-development



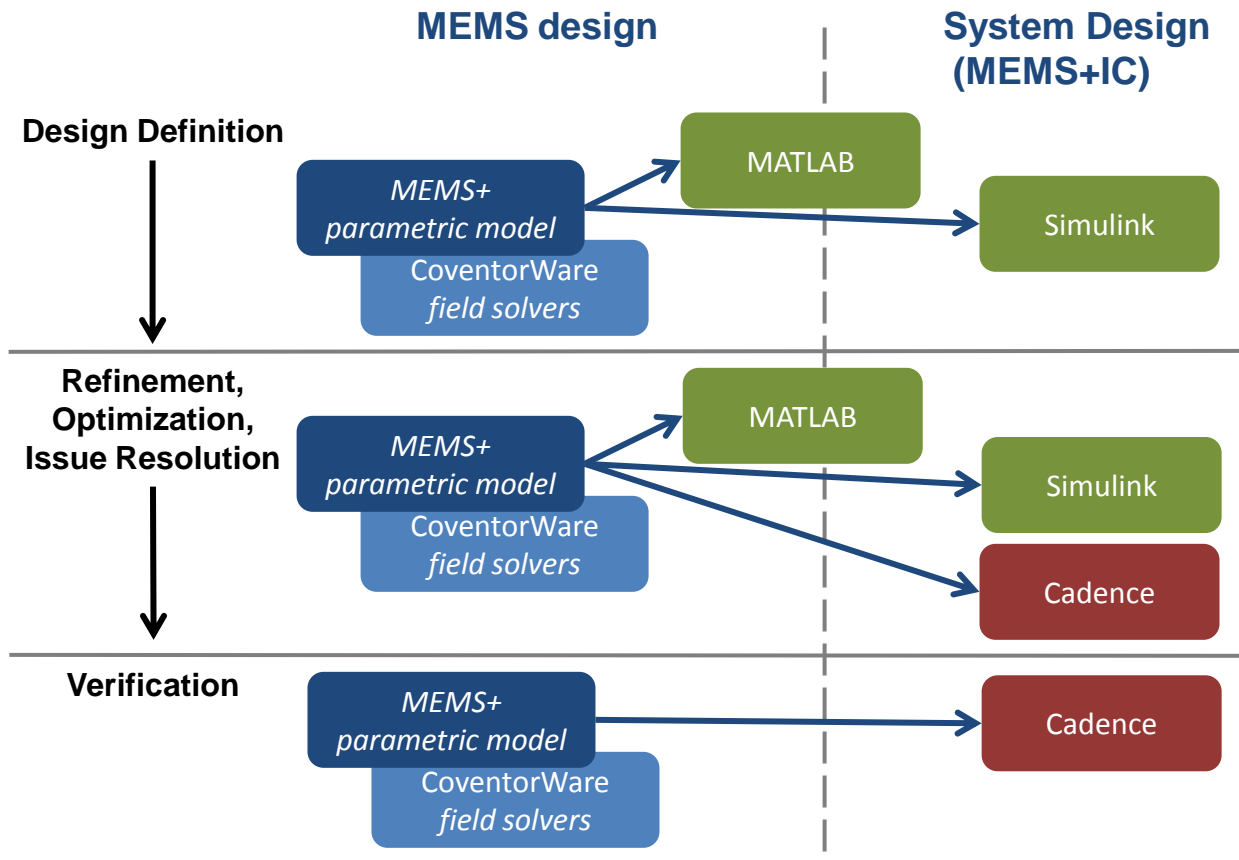
MEMS+



New paradigm for **MEMS+IC** Co-development

A New Paradigm for MEMS+IC Development

COVENTOR



Agenda

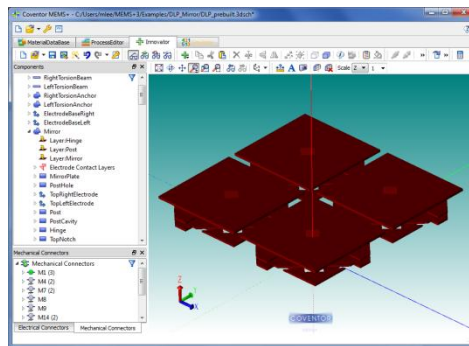
- What is *MEMS+*
- Why use *MEMS+*
- How does *MEMS+* work
- What's New in **MEMS+** 4.0
- Conclusion

What is *MEMS+*?

COVENTOR

A tool for creating **compact finite element models**
that run in MATLAB, Simulink, and Cadence

Enter Design in 3D



Simulate and Analyze

MEMS+ Simulator

MATLAB

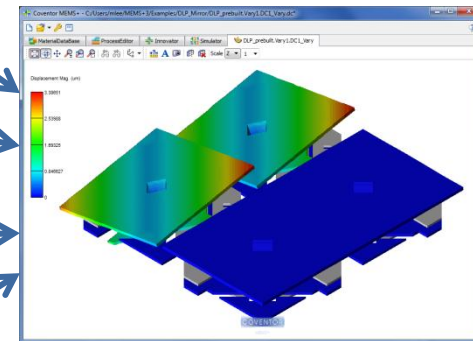


Simulink

cadence

Virtuoso

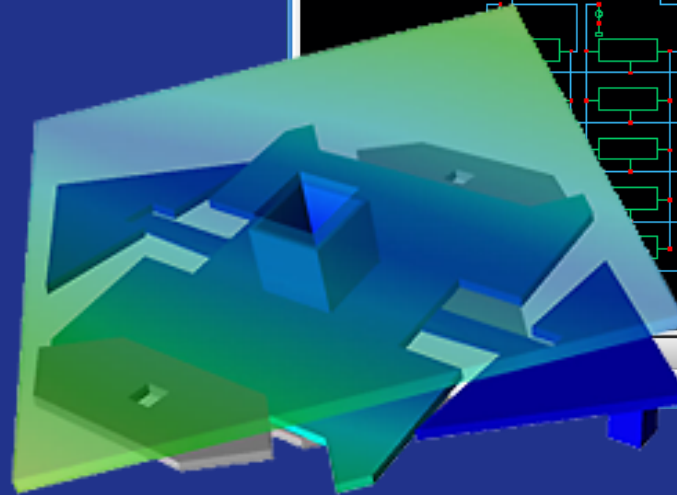
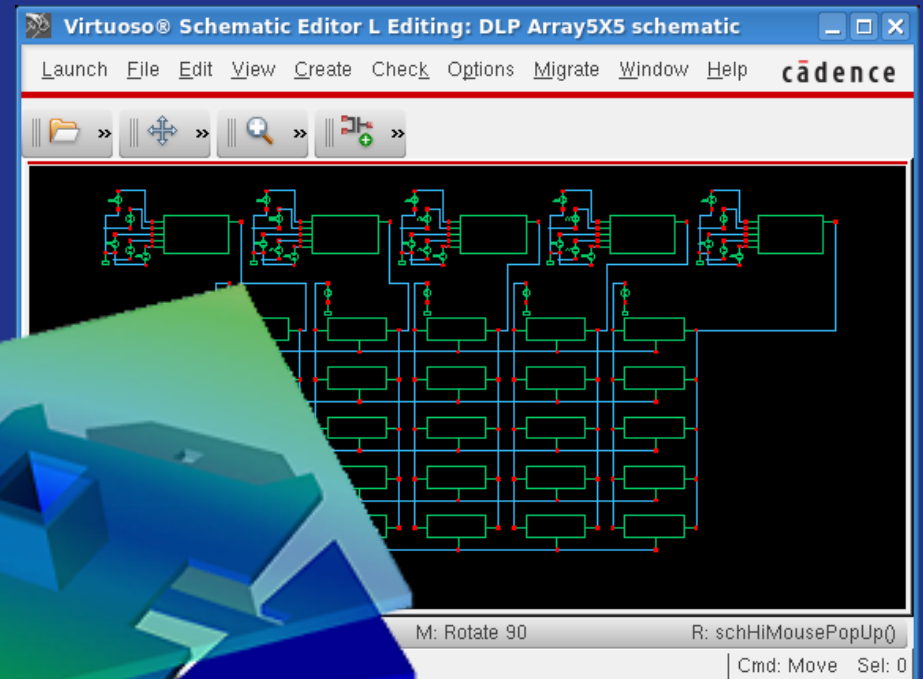
Visualize Results in 3D



***MEMS+* Finite Element Library:**
MEMS-specific, 3D, high-order, parametric

Why Use MEMS+ ?

or what MEMS+ can do for you...



MEMS present specific simulation challenges

MEMS are multi-physics

Mechanics
+ electrostatics
+ fluidic effects
+ packaging effects
+ etc.

MEMS+ can simulate fully coupled physics

- Dynamic response
- Rapid design studies
- Design optimization

MEMS are part of a system

- MEMS + control system
- MEMS + IC

MEMS+ models work in system and IC tools

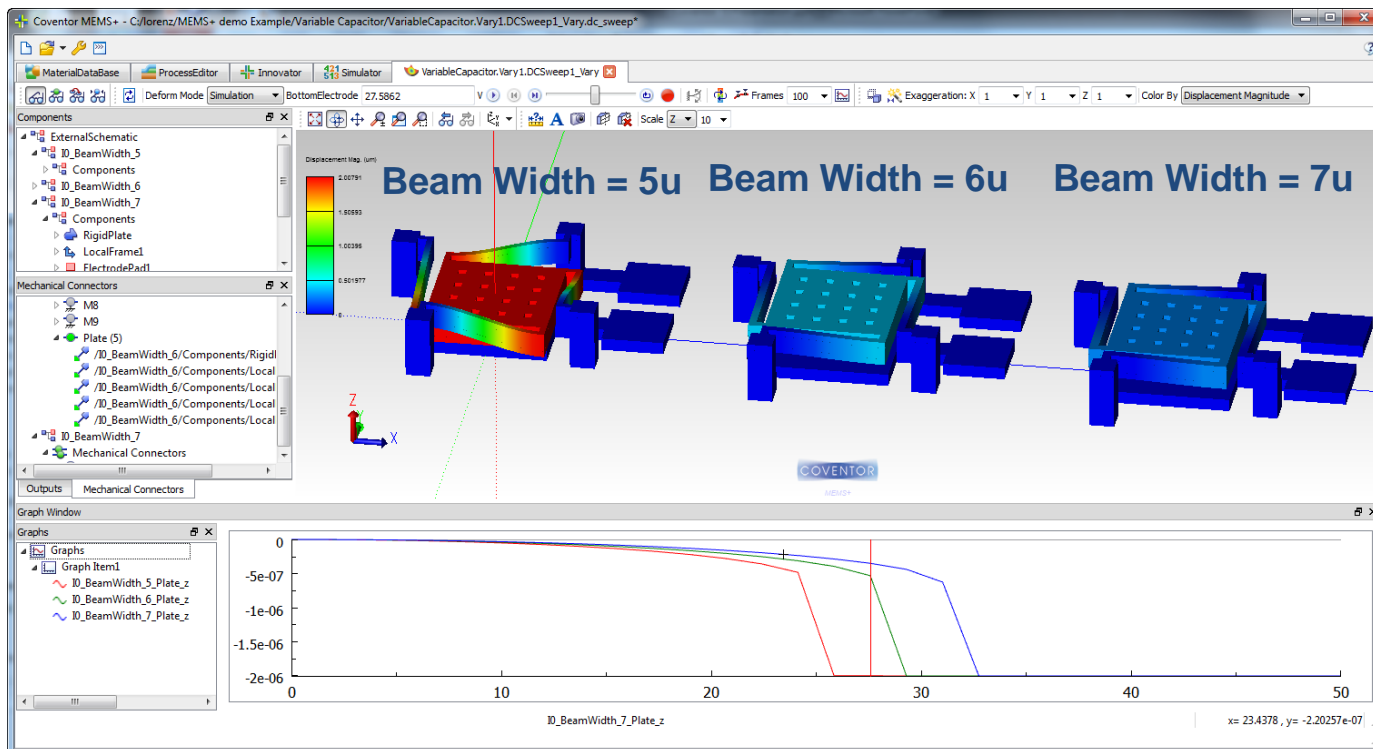
- Closed-loop operation
- Noise analysis
- Device arrays

Why use *MEMS+*? MEMS are multi-physics

COVENTOR

Need to quickly evaluate design concepts?

MEMS+ has an easy-to-use UI for building parametric models, with built-in simulator, and MATLAB and Python scripting interfaces



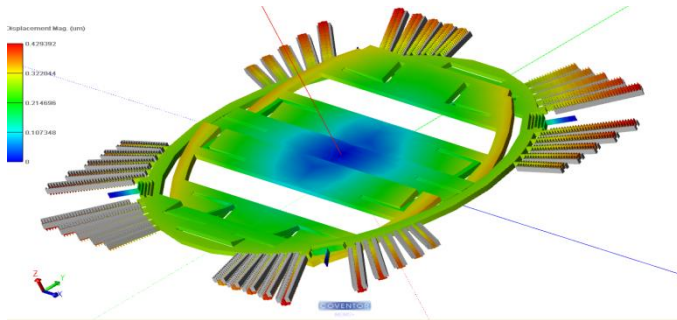
Result of a vary analysis exploring different design geometries

Why use *MEMS+*? MEMS are multi-physics

COVENTOR

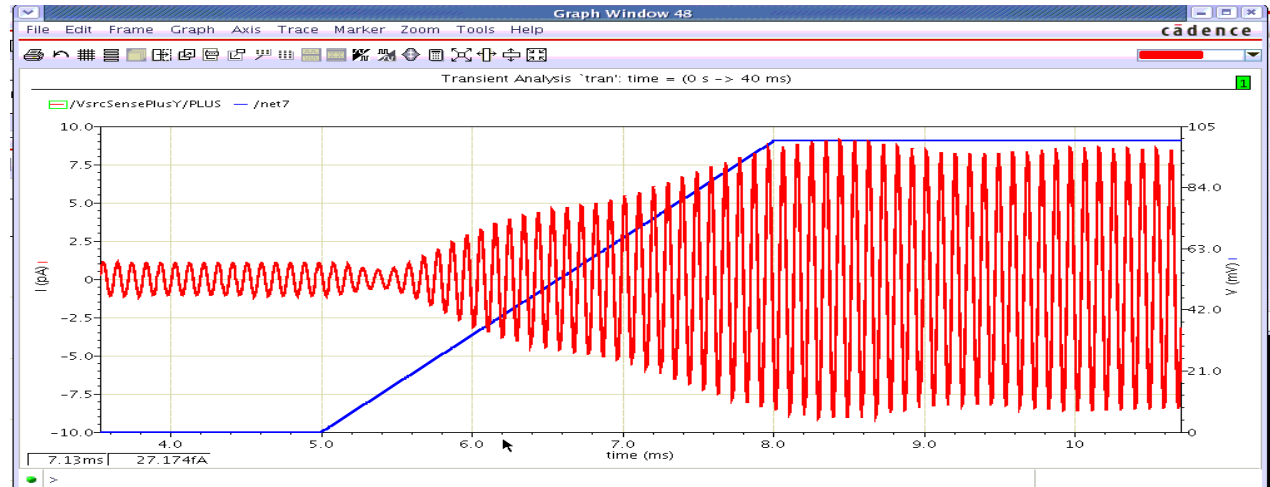
Need to study the dynamic response of your sensor?

MEMS+ model of a gyroscope,



MEMS+ model includes mechanical, electrical and gas damping effects, and is small enough for fast transient simulations in Simulink or Cadence

Transient response to angular acceleration, simulated in minutes on a laptop

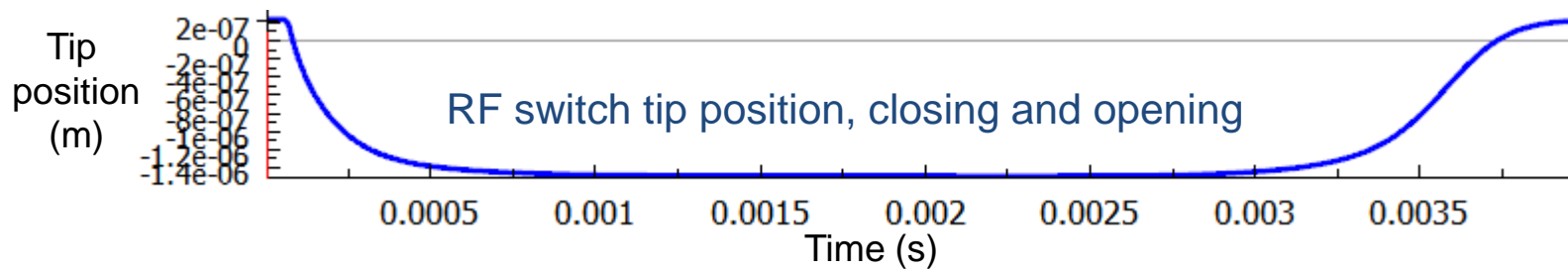
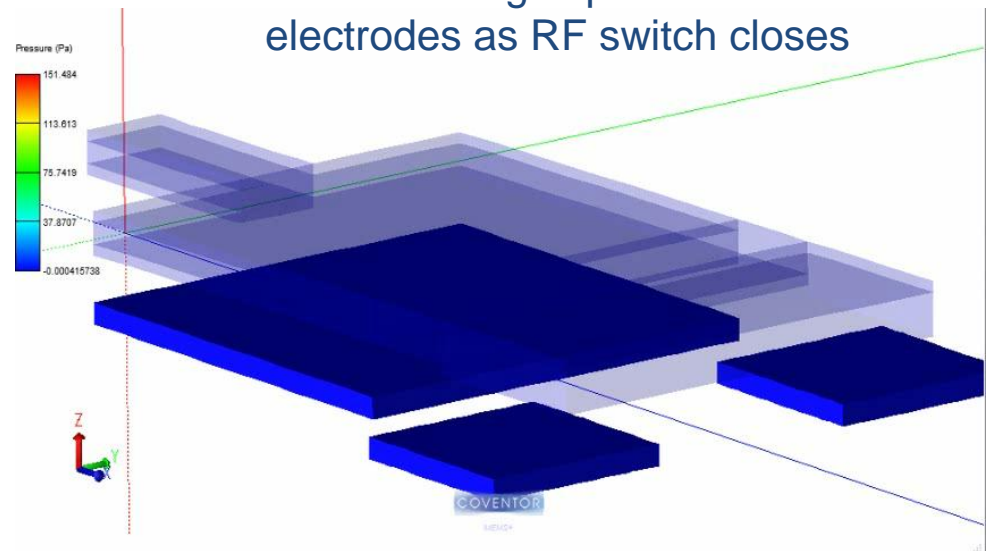


Why use *MEMS+*? MEMS are multi-physics

Need to study the dynamic response of your actuator?

MEMS+ models are very fast and can easily combine mechanical, electrical and fluidic effects in a transient simulation

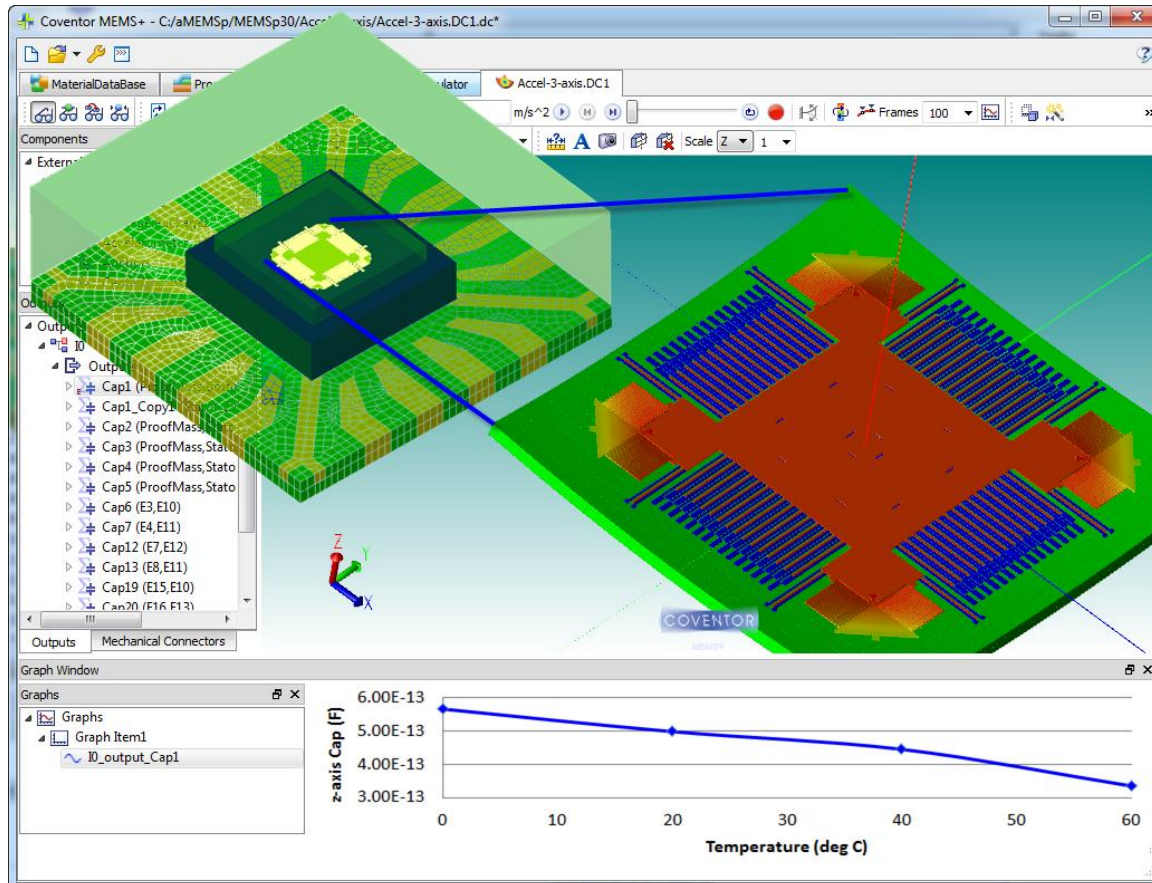
Simulated gas pressure on electrodes as RF switch closes



Why use *MEMS+*? MEMS are multi-physics

COVENTOR

Need to assess packaging effects on your sensor?



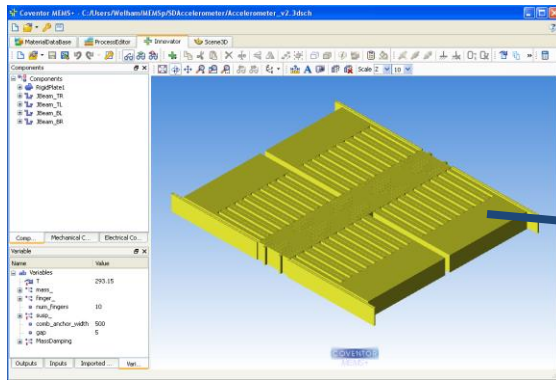
MEMS+ can predict how thermal effects on your package will affect critical sensor outputs such as zero-offset in accelerometers

Simulated zero-offset vs. temperature for z-axis of 3-axis accelerometer

Why use MEMS+? MEMS are part of a system

Need to simulate closed-loop control of your sensor?

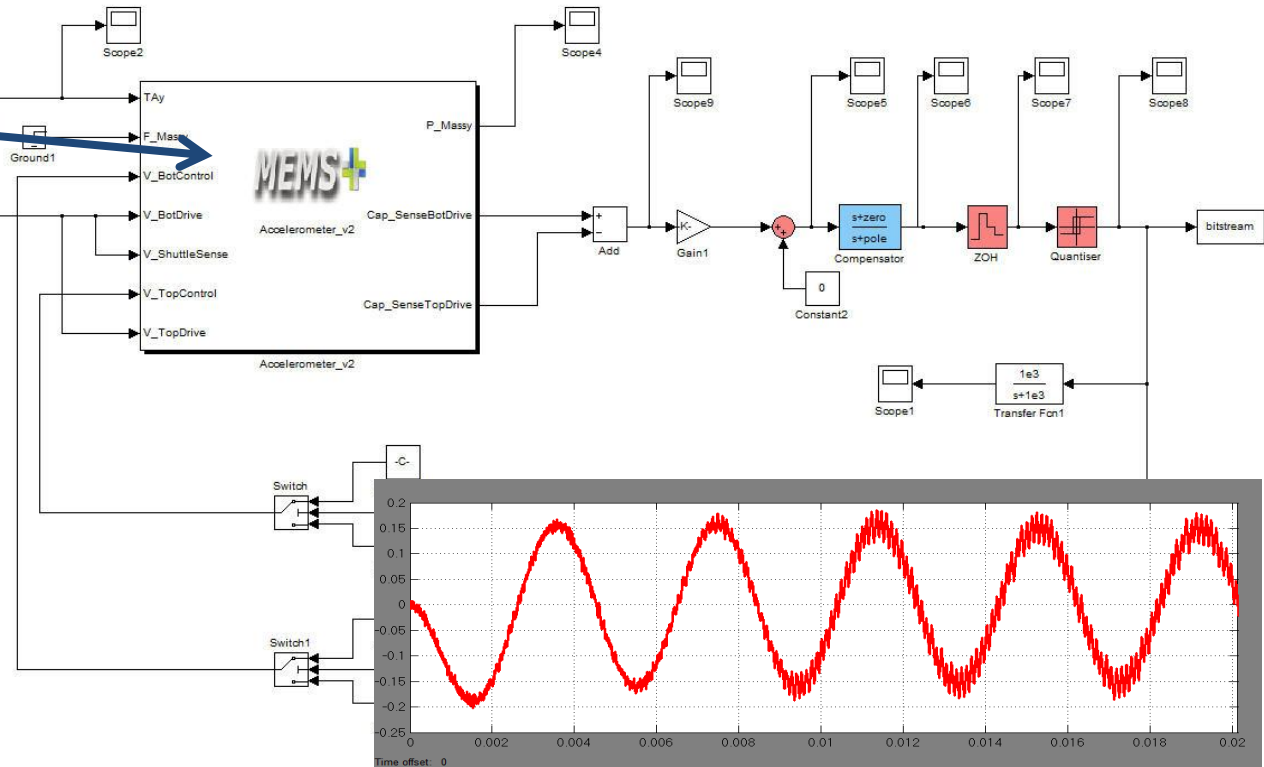
3D accelerometer design in MEMS+



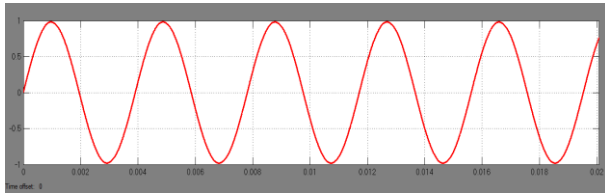
MEMS+ models
plug into Simulink

- Non-linear
- Parametric
- Fast and accurate

Simulink diagram:
accelerometer with sigma-delta controller

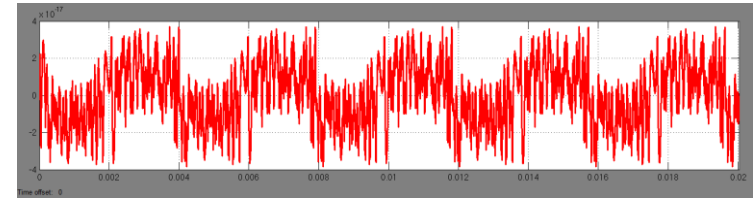


Force-feedback control of accelerometer

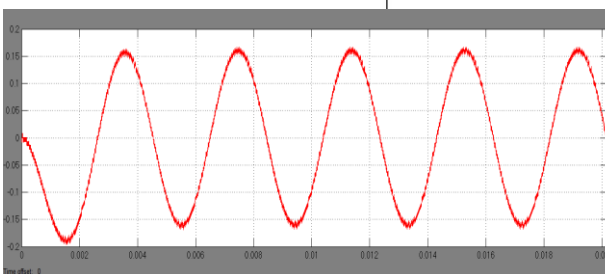
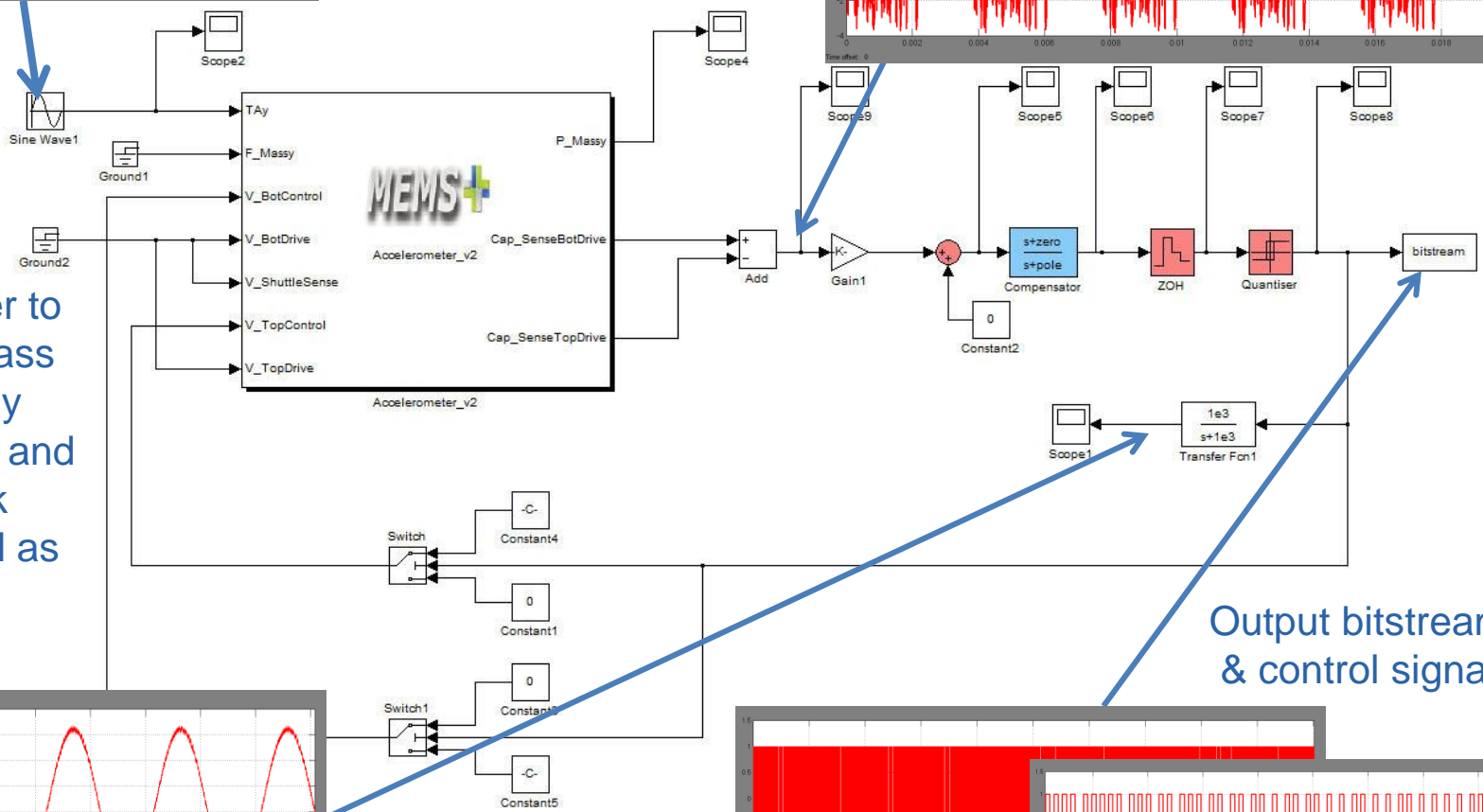


Input acceleration:
 $a_y = \sin(\omega t)$ at 256 Hz

Error capacitance

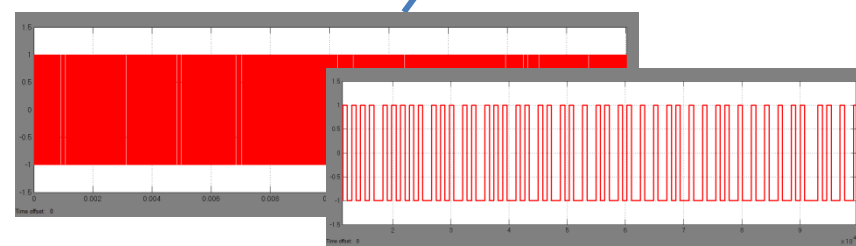


Concept:
Use controller to hold proof mass steady for any acceleration, and use feedback control signal as output.



Low-pass filtered output signal

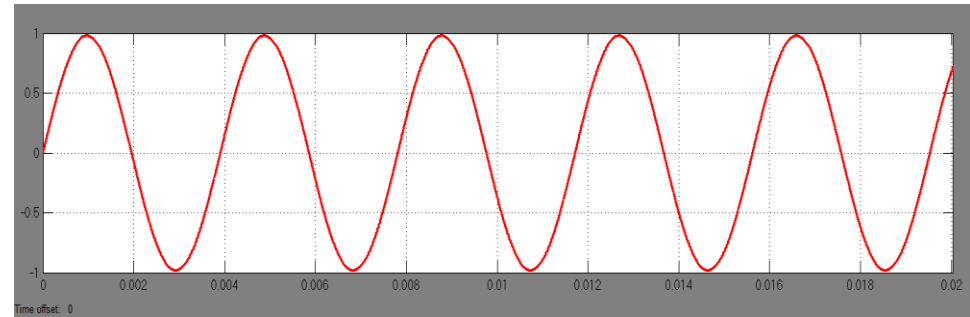
Output bitstream & control signal



System stability simulations in Simulink with *MEMS+* model

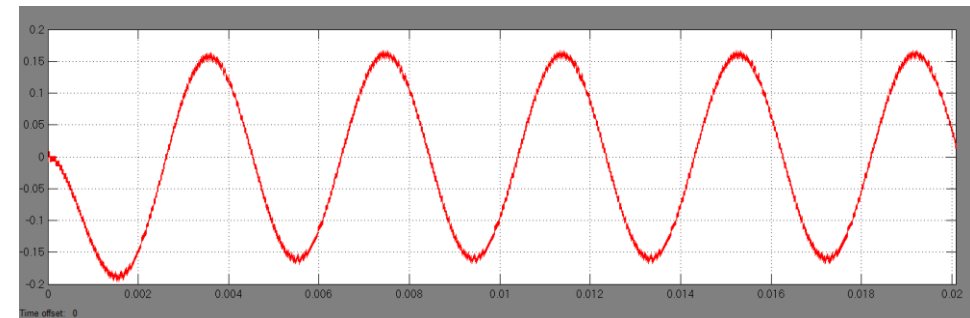
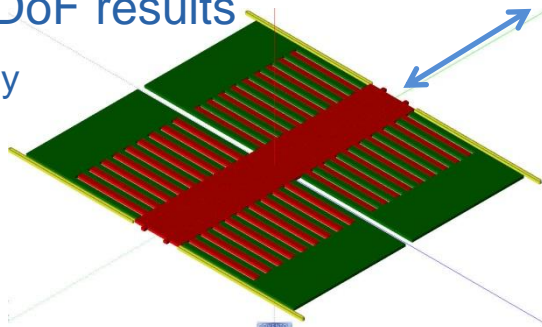
COVENTOR

256 Hz input acceleration



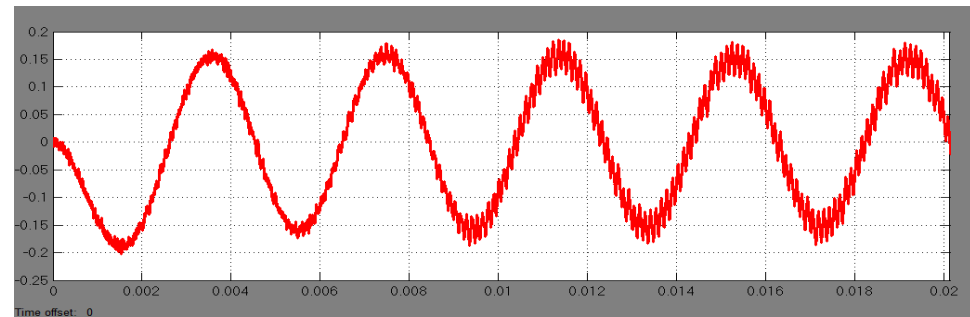
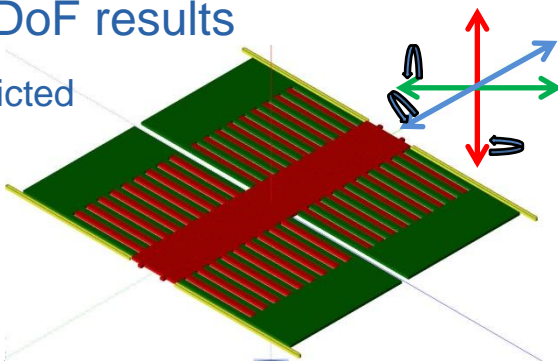
Single-DoF results

y DoF only



Multi-DoF results

Unrestricted motion



Unstable: "Noise" grows until the combs pull-in!

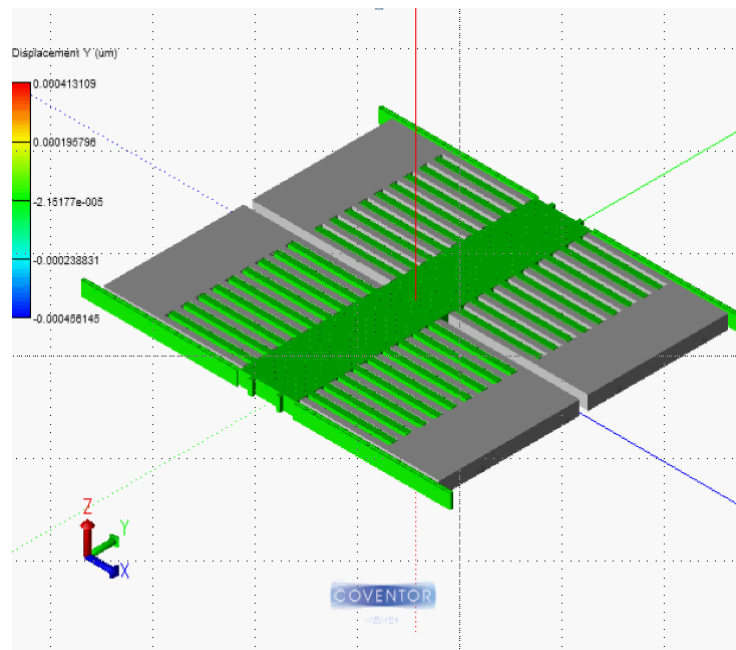
System stability simulations MEMS are part of a system

COVENTOR

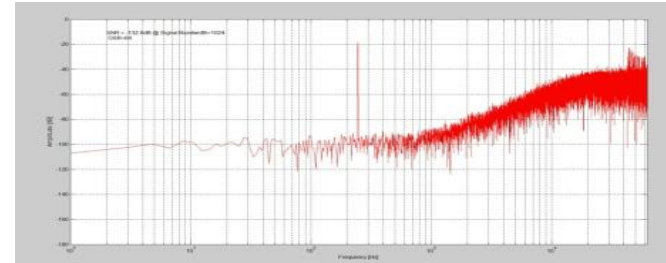
Need help to understand your measured results?

Instead, load into *MEMS+* to visually
observe device behavior:

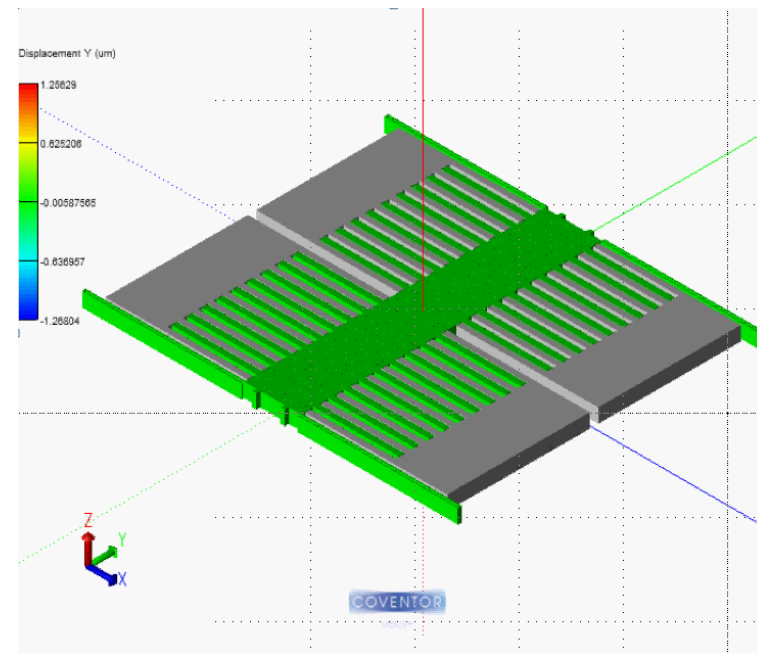
1-DOF model in *MEMS+*



1-DOF model erroneously considers
the system stable



Multi-DoF model *MEMS+*



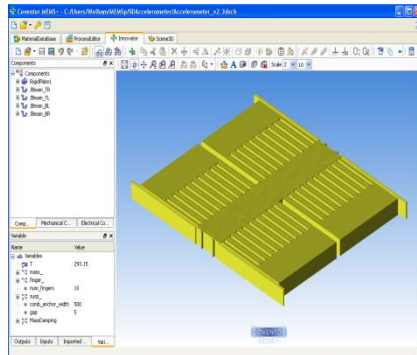
Controller excites suspensions
into flapping uncontrollably

MEMS+ models enable parametric studies

COVENTOR

Need to study manufacturability?

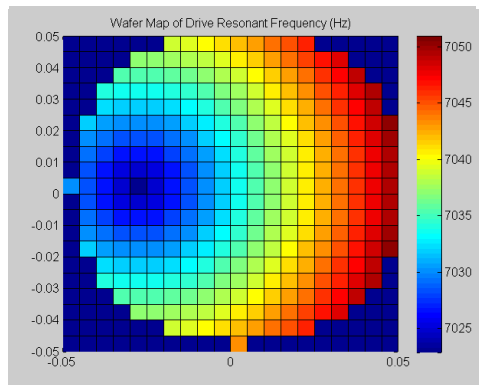
MEMS+
model



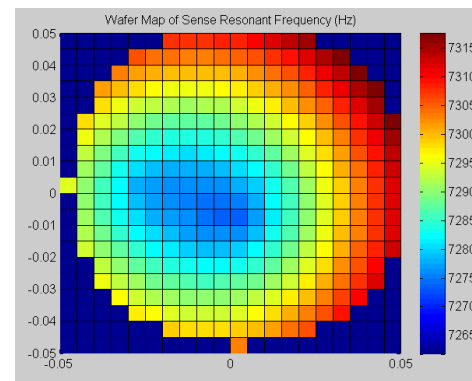
+ MATLAB
script

```
Editor: C:\msdpsp\WaferMap\makeWaferMap.m
File Edit View Cell Tools Debug Desktop Window Help
@ The Runas Cell Mode. For information, see the link: look_help_video, the @ABREQ video, or help.
24 %% Load matrices of wafer data (C_Youngs and Cpoly_thick)
25 - load %loadInputs.mat
26
27 %% Compute device performance
28 MemapSysSystem('mem', 'C:\msdpsp\makeWaferMap.m')
29 %% get the nominal variable values
30 vacs = var2eap(MemapSysSystem('getVariables'));
31 %poly = vacs('Epoly');
32 poly_thickness = vacs('poly_thickness');
33
34 %% Initialize a Wafer map of zeros
35 C_freqHzDrive = zeros(size(Cpoly));
36 C_freqHzSense = zeros(size(Cpoly));
37
38 % previously computed DC soln
39 load %loadInputs.mat
40
41 %% Loop over process data
42 for k=length(Cpoly_thick(i))
43     vacs('Epoly') = Epoly*(1 + C_
44     vacs('poly_thickness') = poly;
45     MemapSysSystem('resetVariables');
46     abcd = MemapSysSystem('getabcd');
47     [shapes, fregsHz] = computeMoc
48     C_freqHzDrive(k) = fregsHz(1);
49     C_freqHzSense(k) = fregsHz(2);
50     if (mod(k,20) == 1) % print k every 20 steps
51         disp(k);
52     end
53 end
54
```

10 minutes CPU time
to compute 400 mode
frequencies



Y-mode Frequency



Z-mode Frequency

Example: Modal frequencies vs. process variations across wafers

Why use *MEMS+*?

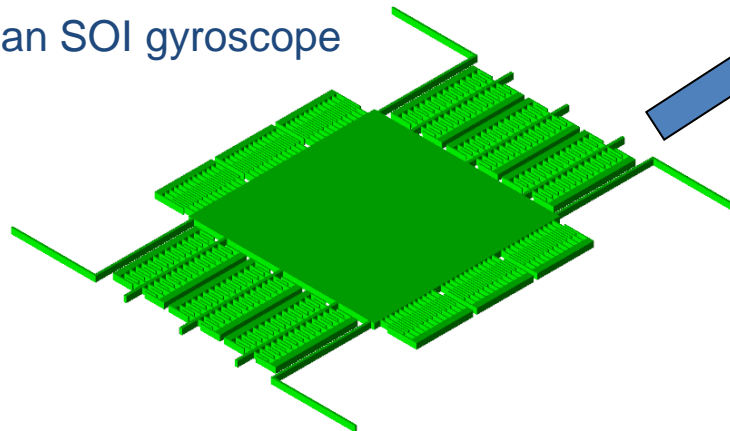
MEMS are part of a system

Need to provide a MEMS model to your IC designers?

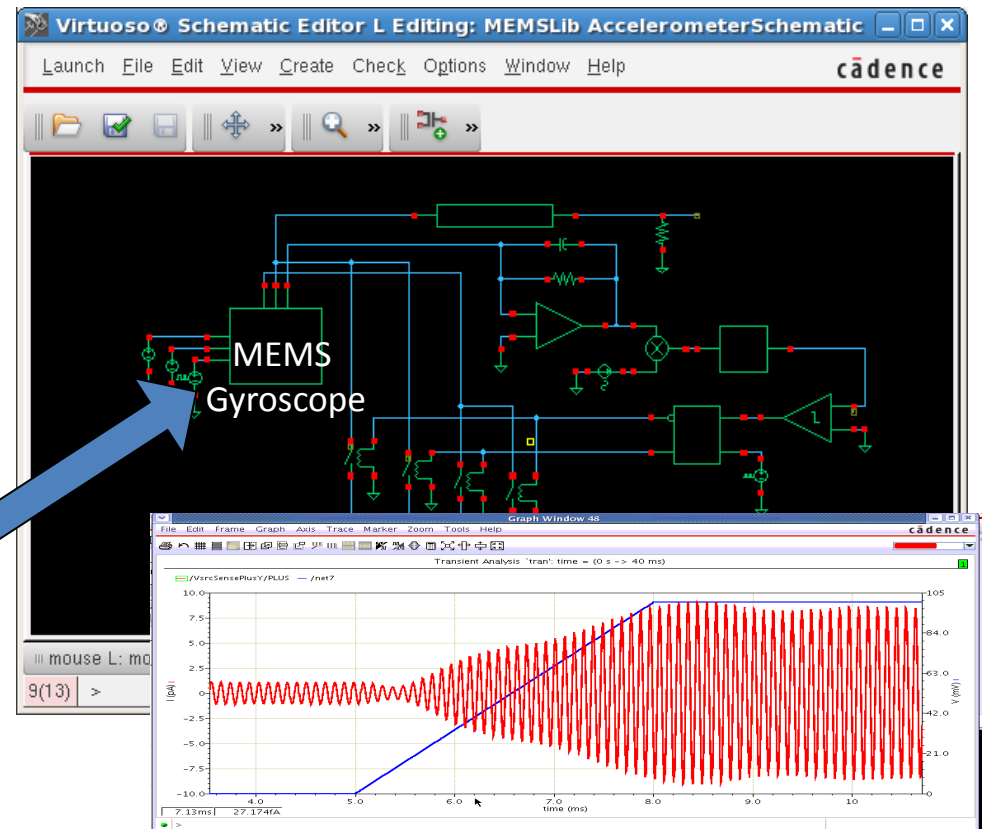
Import a *MEMS+* model to a Cadence Virtuoso schematic with a few button clicks

- Include all essential nonlinearities
- Selectively linearize for speed

MEMS+ model of an SOI gyroscope



Cadence Virtuoso schematic



Why use *MEMS+*?

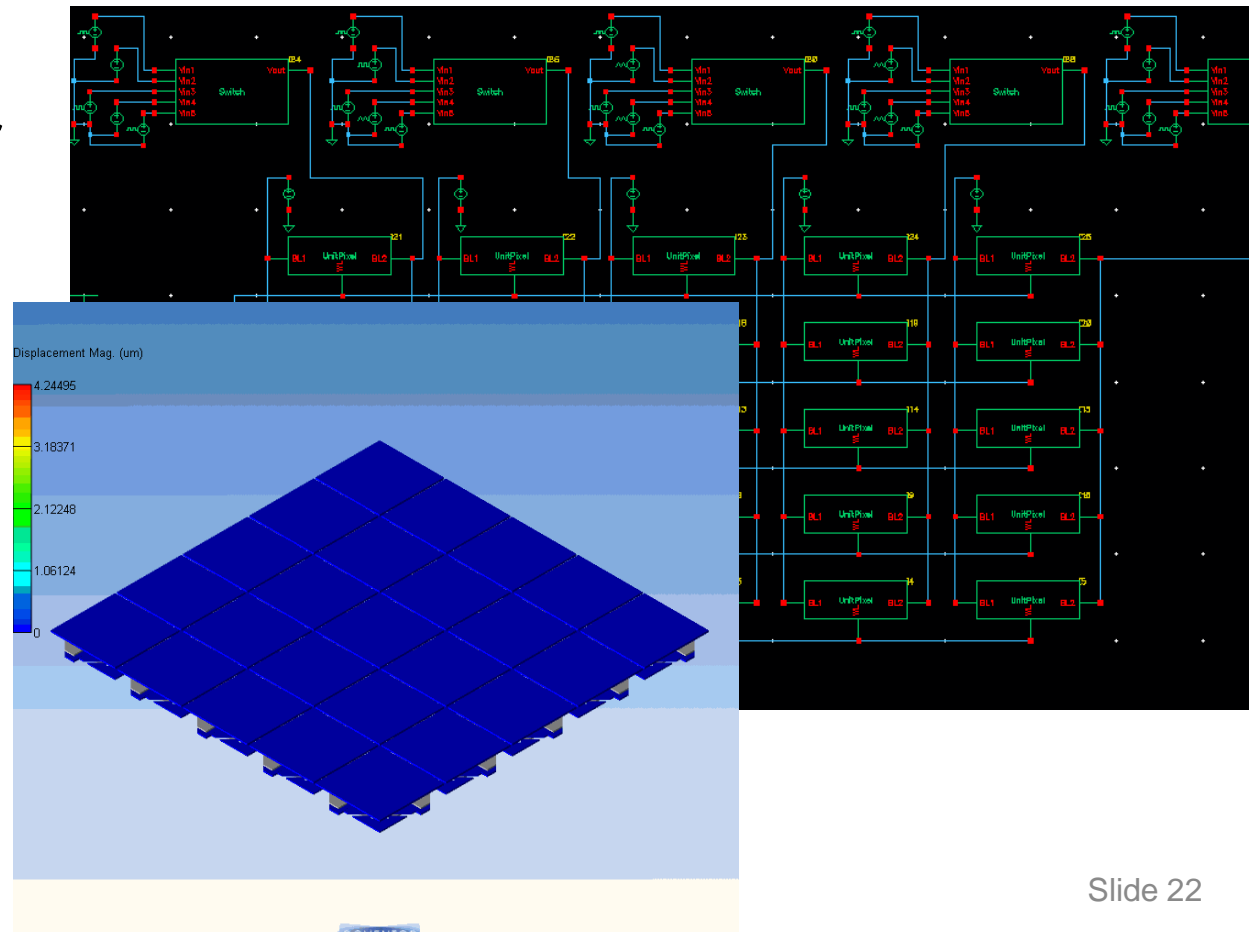
MEMS are part of a system

Need to simulate an array of actuators?

MEMS+ models capture non-linear effects and simulates fast

Cadence Spectre simulation results visualized in *MEMS+*

Cadence Virtuoso schematic of a mirror array

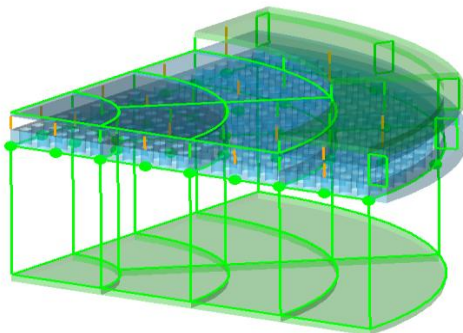


Why use *MEMS+*? MEMS are part of a system

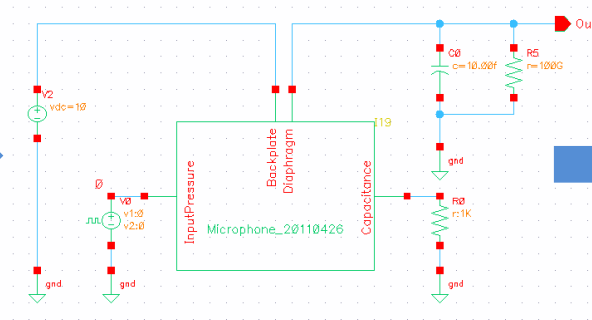
Need to perform noise analysis of your sensor?

- *MEMS+* models support noise analysis in Cadence Spectre and accurately predict thermo-mechanical noise
- *MEMS+* includes all relevant noise sources in your *MEMS+*IC system, enabling you to improve your signal to noise ratio

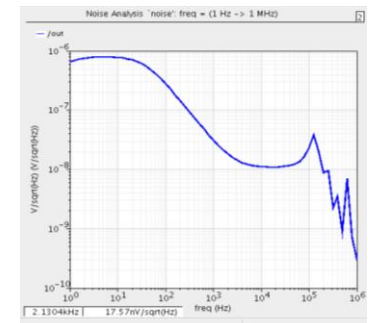
MEMS+ model of a microphone



MEMS+ model includes mechanics, electrostatics and fluidics (air pressure) effects



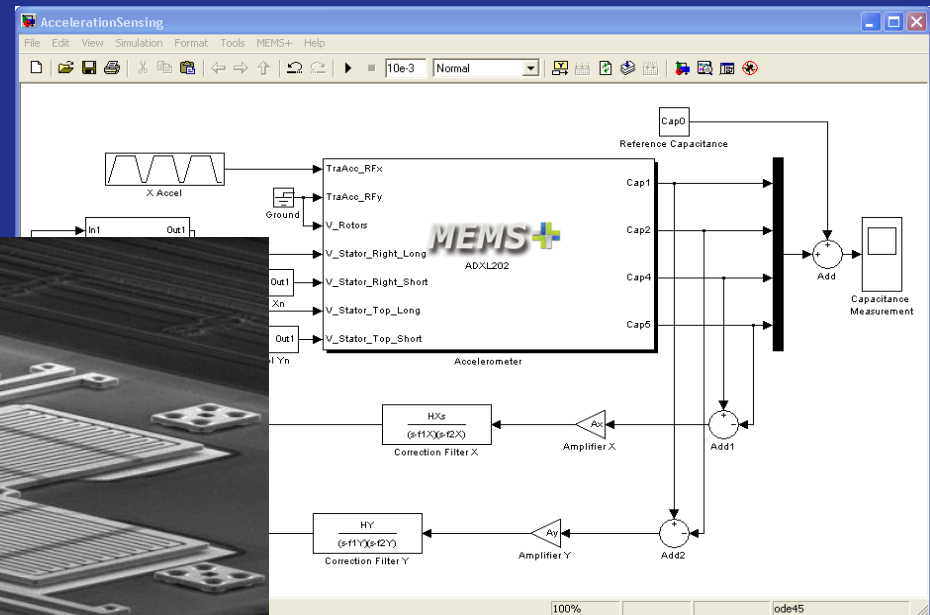
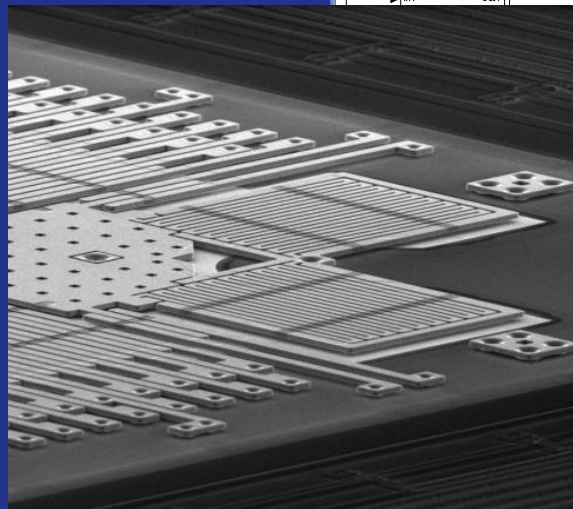
MEMS+ symbol in a Cadence Virtuoso schematic



Noise analysis in Cadence Spectre

How does MEMS+ work?

or how to create compact FE model...

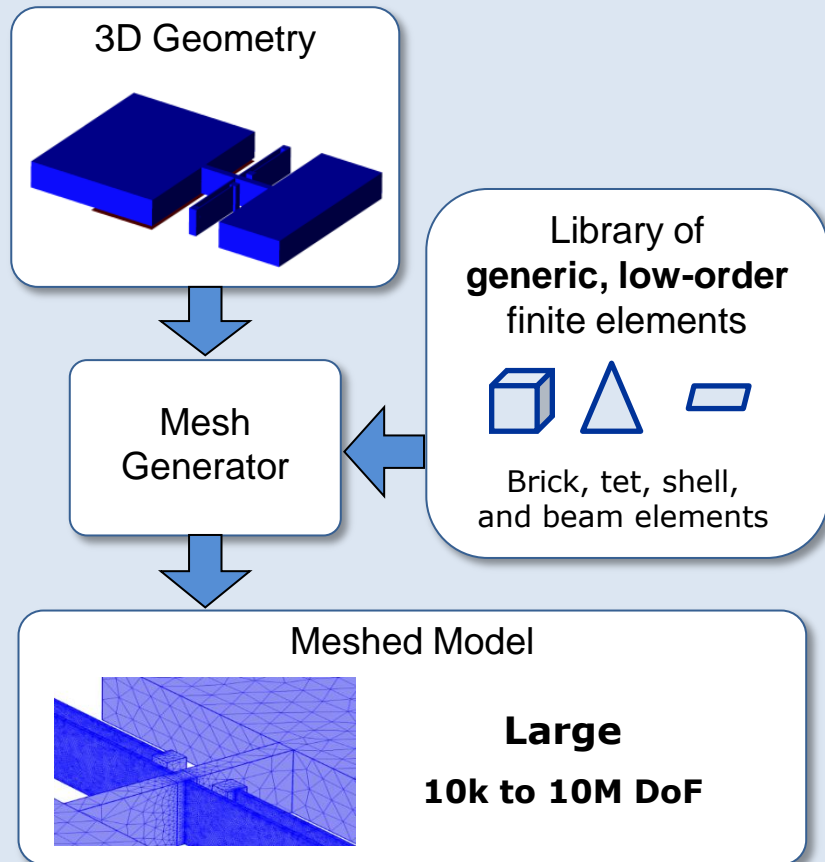


MEMS+

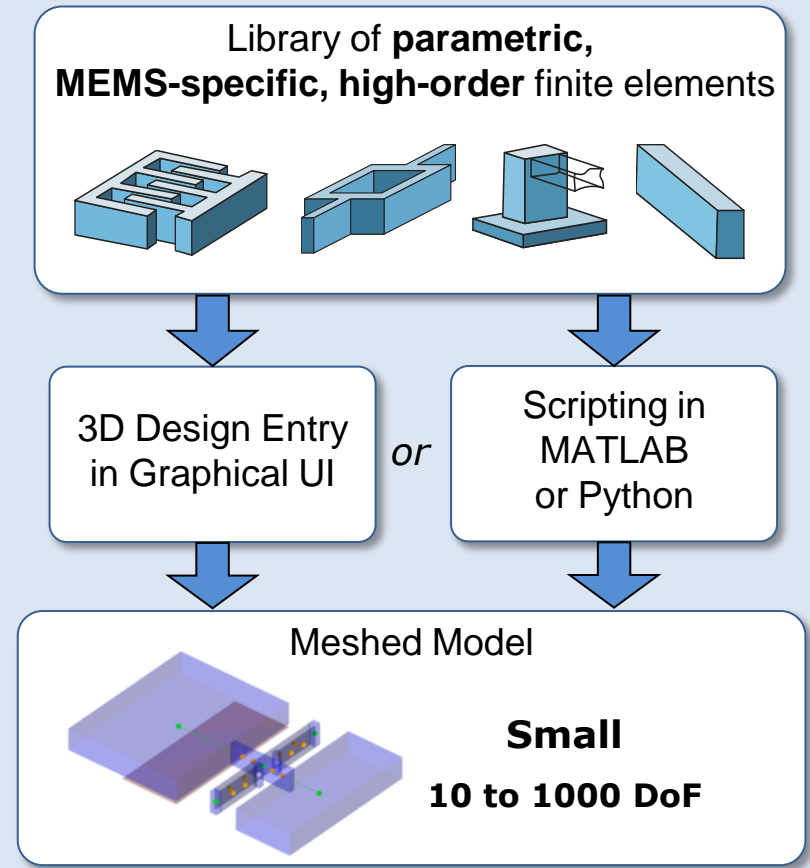
a different kind of FEA

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Traditional Finite Element Analysis



MEMS+ Finite Element Analysis

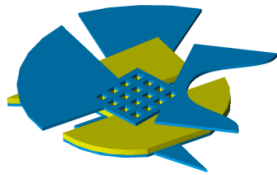


Overview of the *MEMS+* Element Library

COVENTOR

Start with
Mechanical
Components

Rigid Shapes



Flexible Shapes



Beams

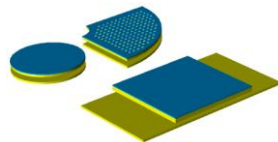


Suspensions

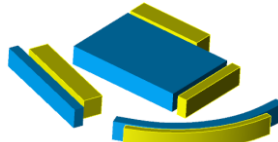


Add Electro-
Mechanical
Coupling

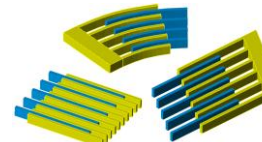
In-Plane
Electrodes



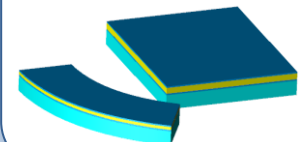
Side
Electrodes



Interdigitated
Combs



Piezo
Layers

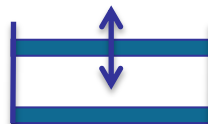


Add Fluid
Damping
and Loading

Squeezed-Film
Damping



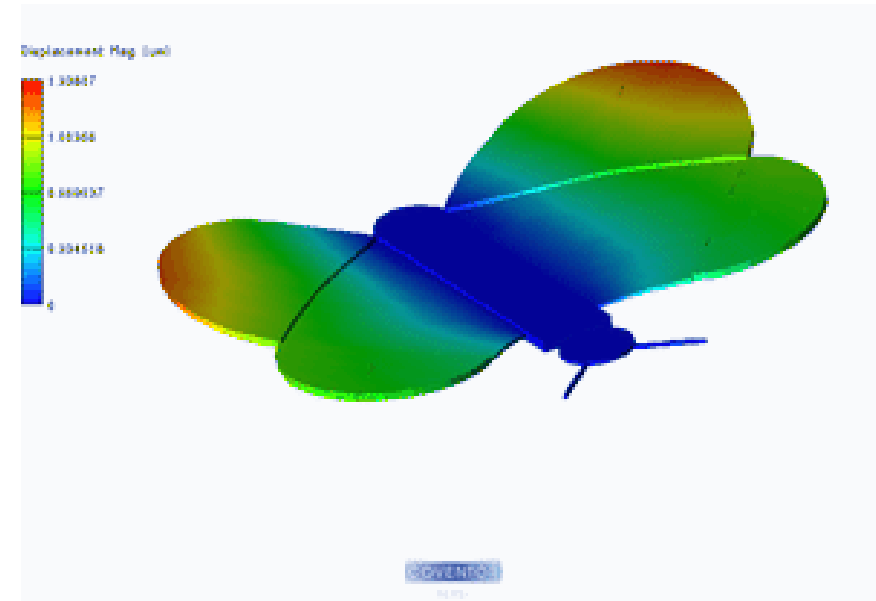
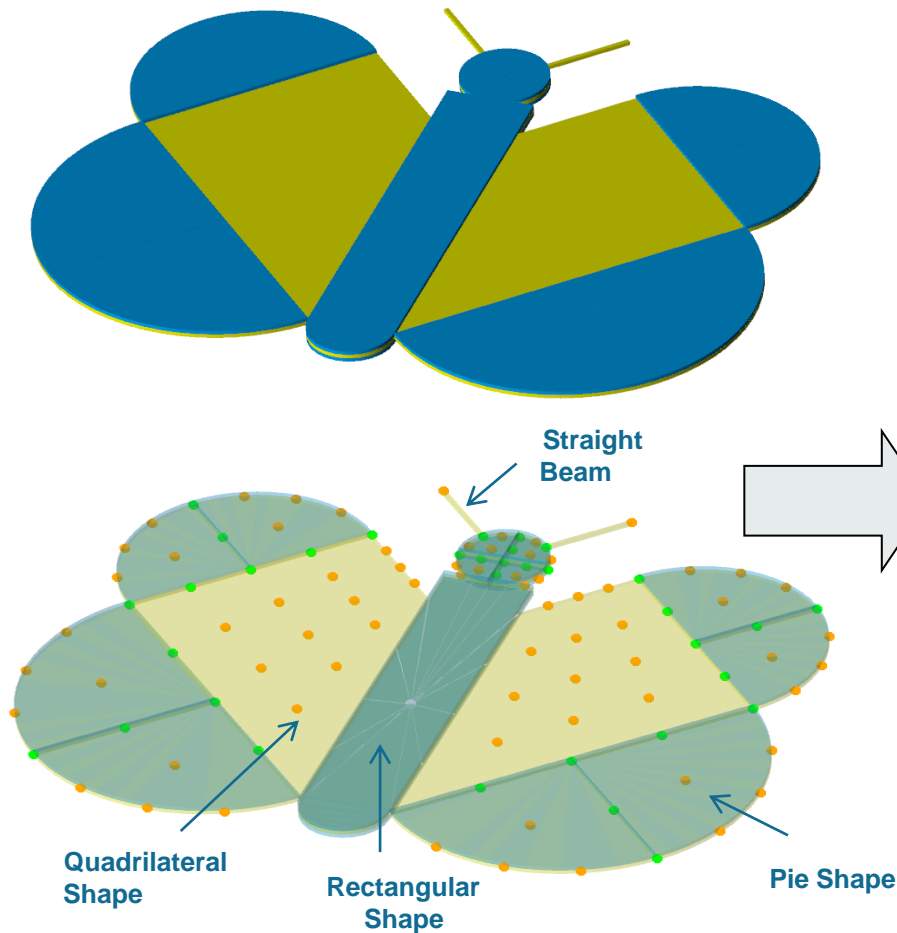
Fluid
Chambers



Pressure
Loads



Users assemble MEMS-specific, high-order finite elements to create complex structures:

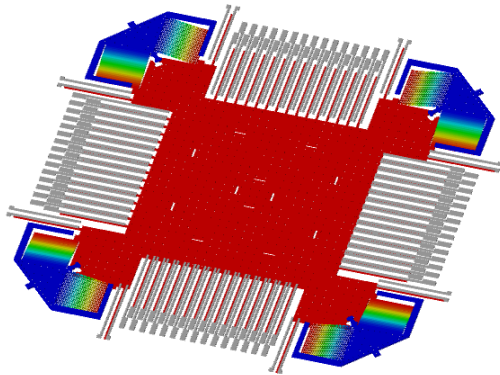


MEMS+

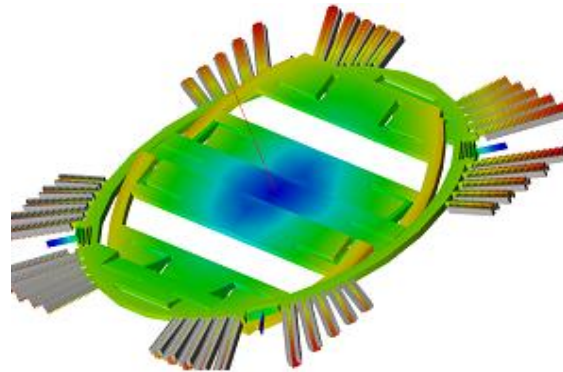
Application Examples

COVENTOR

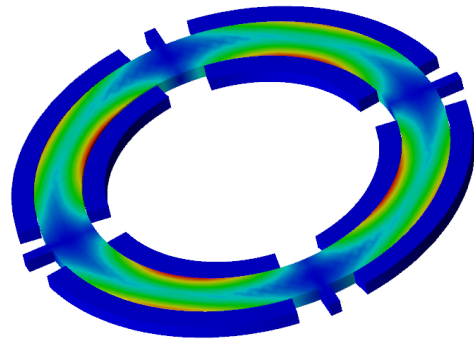
Accelerometer, 67 DoF



Gyroscope, 96 DoF

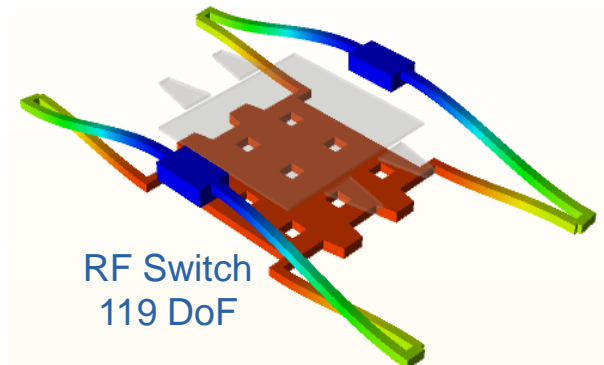
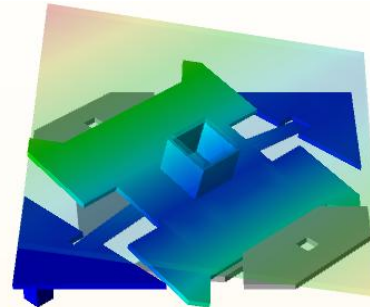


Ring Gyro, 345 DoF



Ring Resonator, 727 DoF

DLP mirror, 11 DoF



RF Switch
119 DoF

The MEMS+ approach is general: it has been used to create compact, accurate models of many real-world MEMS designs

Benefits of the MEMS+ high-order FEM approach:

➤ **Simulation Speed**

➤ **Parameterization**

➤ **Compatibility**

MEMS+ Benefit: Simulation Speed

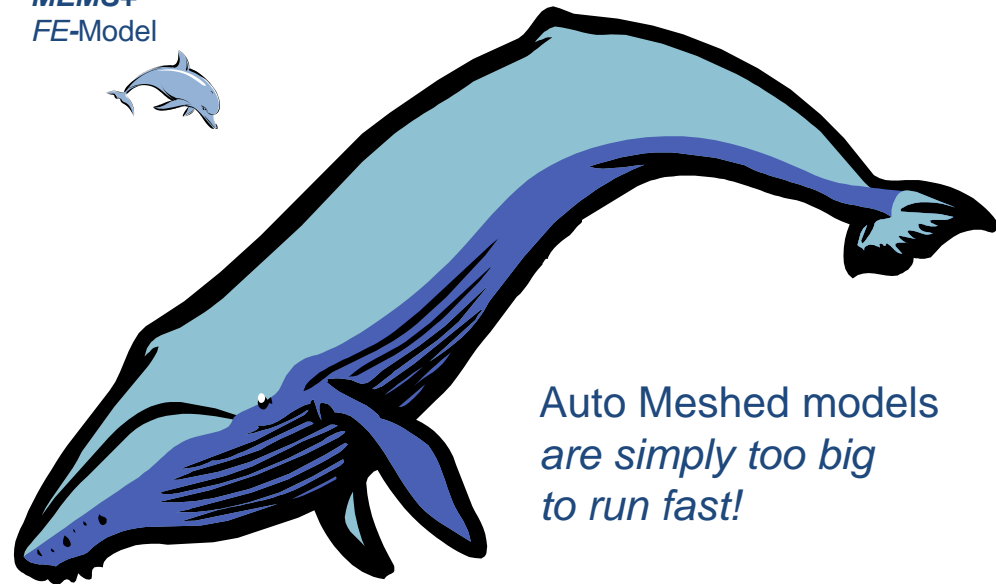
COVENTOR

- Auto-meshed models are huge and require long simulation times
- **MEMS+** models are tiny in comparison

User Benefits:

- Multi-physics analysis in minutes
- Transient simulations in minutes or hours
- Arrays

MEMS+
FE-Model

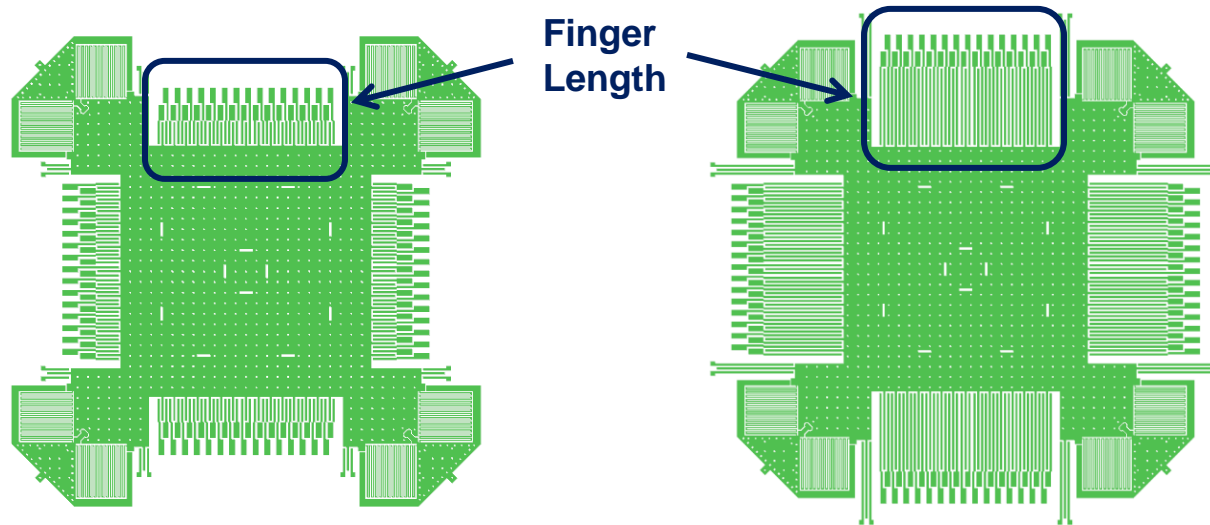


*Auto Meshed models
are simply too big
to run fast!*

MEMS+ Benefit: Parameterization

- **MEMS+** offers a direct way to create efficient parametric models using high-order, MEMS-specific finite elements

Parameters may include geometric, process, material and environmental variables

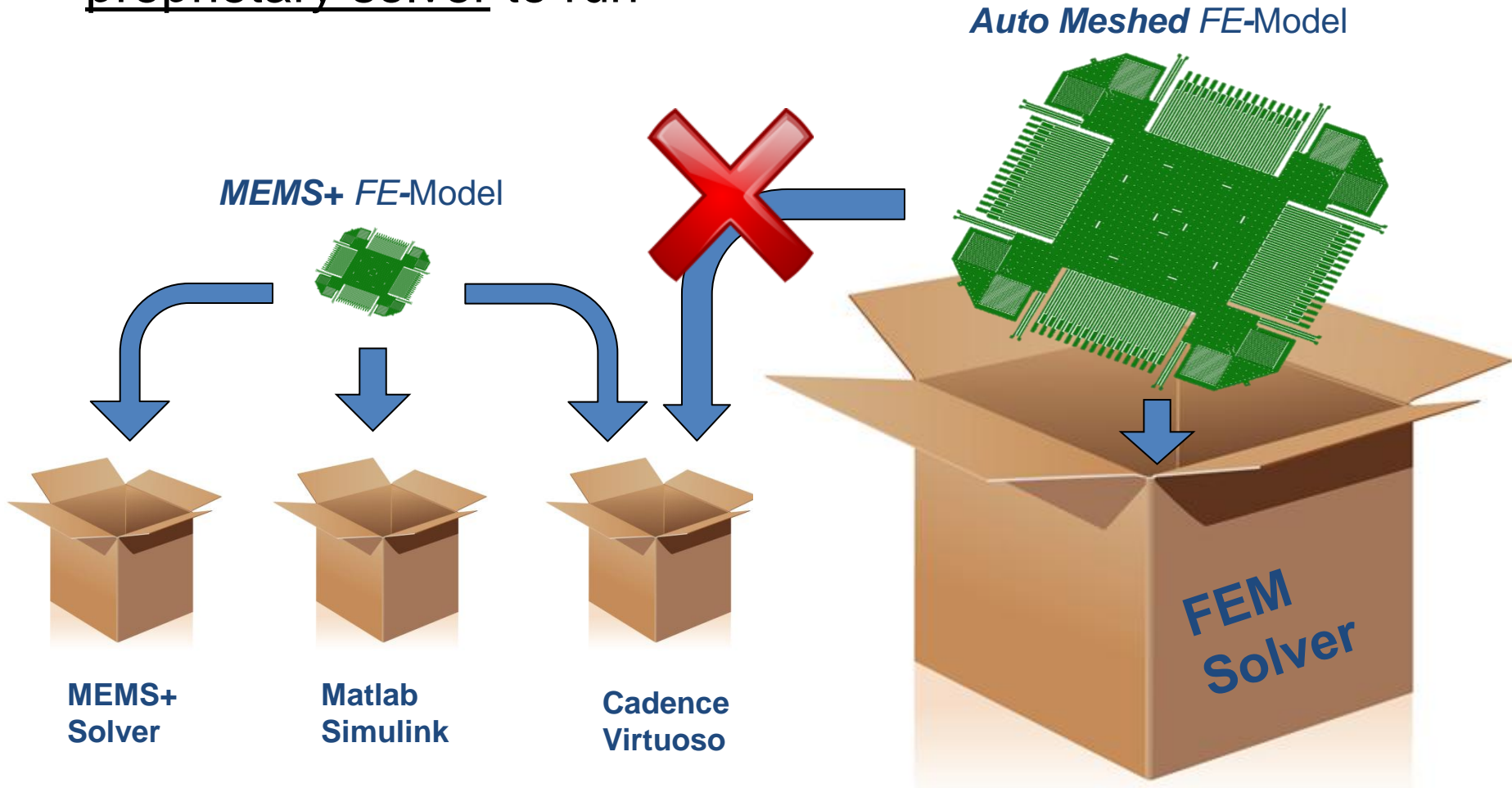


- Enables design optimization, parameter studies, sensitivity, yield and Monte Carlo analysis

MEMS+ Benefit: Compatibility

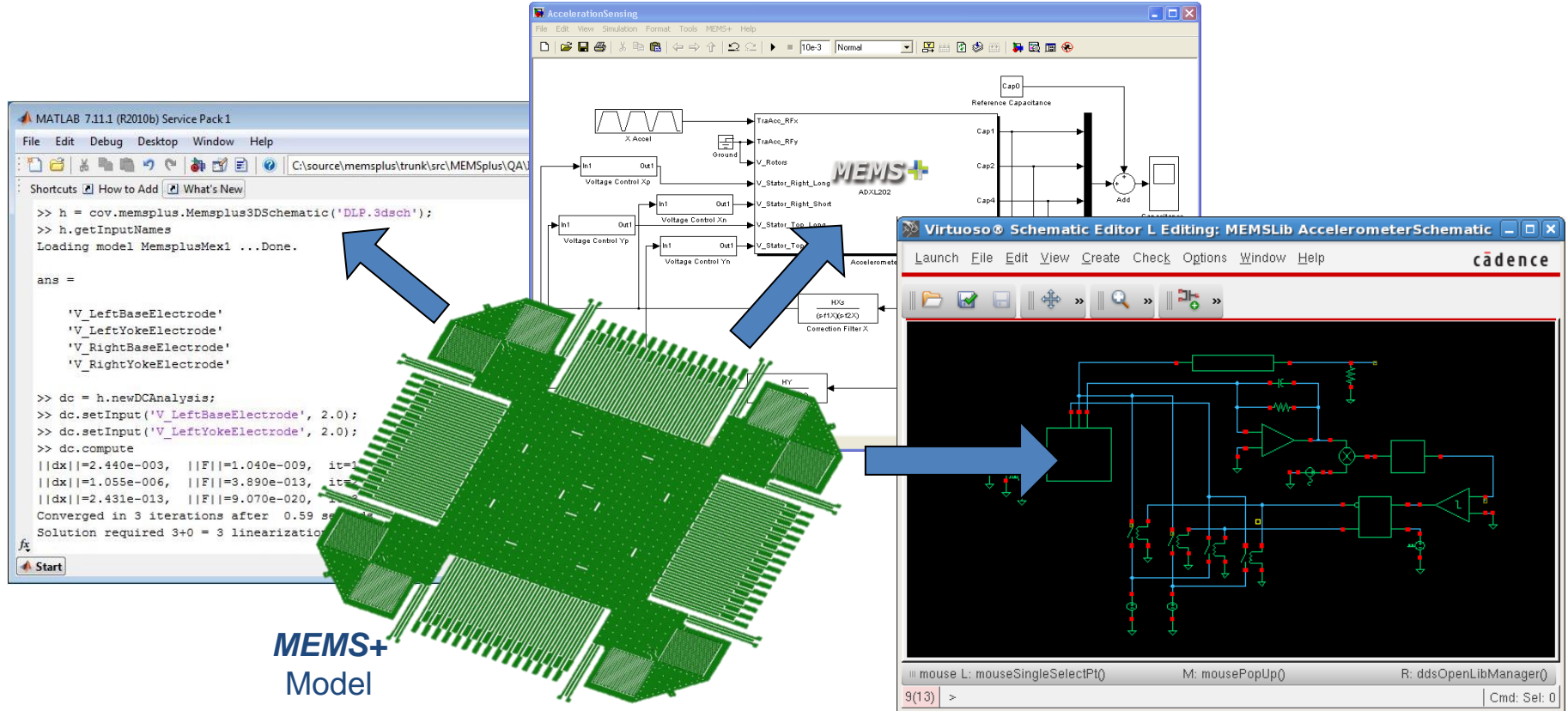
COVENTOR

- Auto-meshed models are huge and require proprietary solver to run



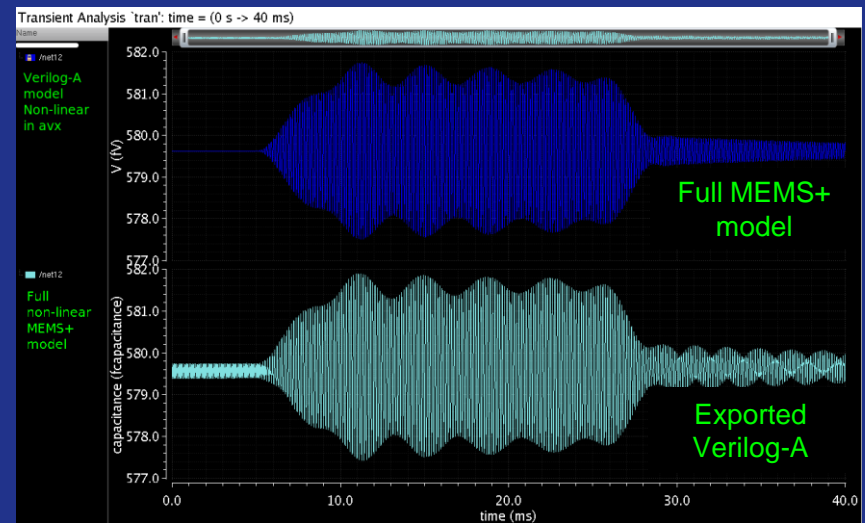
MEMS+ Benefit: Compatibility

COVENTOR



- Enables system level, MEMS/IC co-simulation and noise analysis
- Provides access to many existing tool boxes for design and system optimization

What's New in *MEMS+* 4.0 — a new paradigm for MEMS+IC co-design



A large, bright green arrow pointing to the right, highlighting the first section header.

Ability to export models in Verilog-A format

- Exported models simulate up to 100X faster
- Compatible with most A/MS simulators, not just Cadence
- Enables MEMS designers to share models with ASIC developers

More capacity and speed...

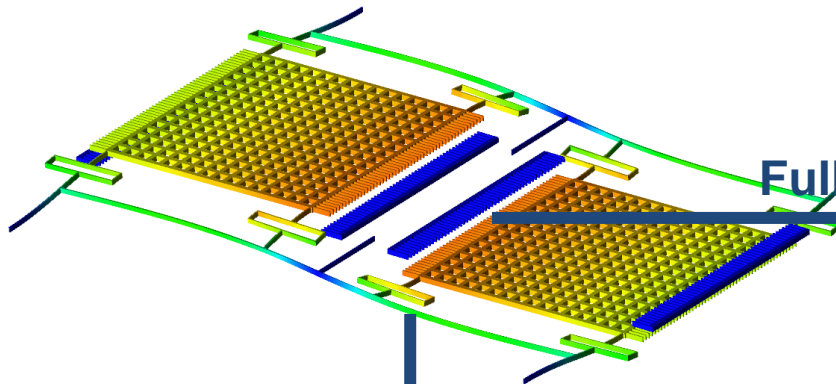
- Full 64-bit implementation to handle larger, more detailed models
- New sparse solver for modal analysis
- Faster loading of large models

More modeling options...

- New geometry options for curved combs, useful in gyro designs
- Selectively include fringing fields for in-plane motion
- Out-of-plane angle and length scale for imported package
- Save reaction forces and moments for verification

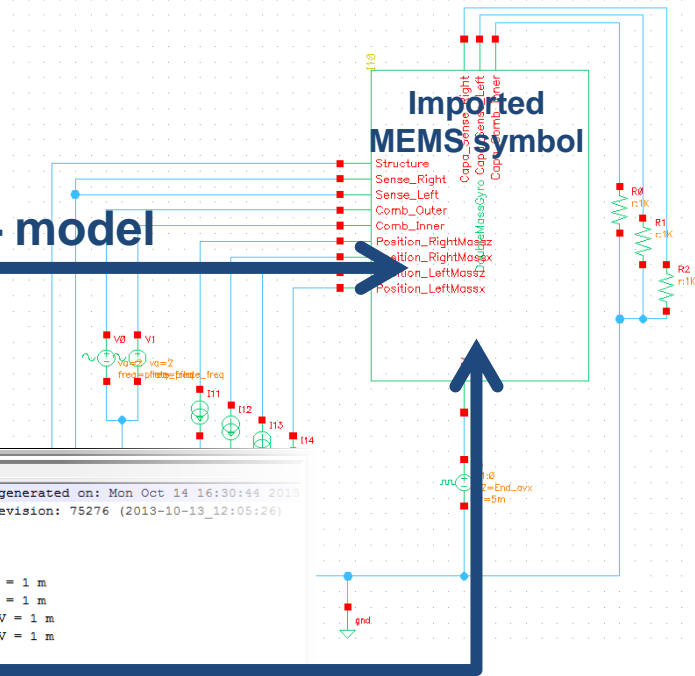
MEMS+ 4.0 offers two paths to MEMS+IC co-design

MEMS+ model



Full MEMS+ model

MEMS+IC schematic



Exported Verilog-A

```
DoubleMassGyroModelExport1.va
1 // Verilog-A model automatically generated on: Mon Oct 14 16:30:44 2013
2 // with: MEMS+ 4.0.0, Revision: 75276 (2013-10-13 12:05:26)
3 //
4 // Useful scale factors:
5 //
6 // Position_LeftMass_x : 1e+006 V = 1 m
7 // Position_LeftMass_z : 1e+006 V = 1 m
8 // Position_RightMass_x : 1e+006 V = 1 m
9 // Position_RightMass_z : 1e+006 V = 1 m
10 // Comb_Inner : 1 V = 1 V
11 // Comb_Outer : 1 V = 1 V
12 // Sense_Left : 1 V = 1 V
13 // Sense_Right : 1 V = 1 V
14 // Structure : 1 V = 1 V
15 // avy : 0.0001 V = 1
16 //
17 // Outputs scale factors:
18 //
19 // Capa_Comb_Inner : 1 V = 1 F
20 // Capa_Sense_Left : 1 V = 1 F
21 // Capa_Sense_Right : 1 V = 1 F
22 //
23 //
24 //
```

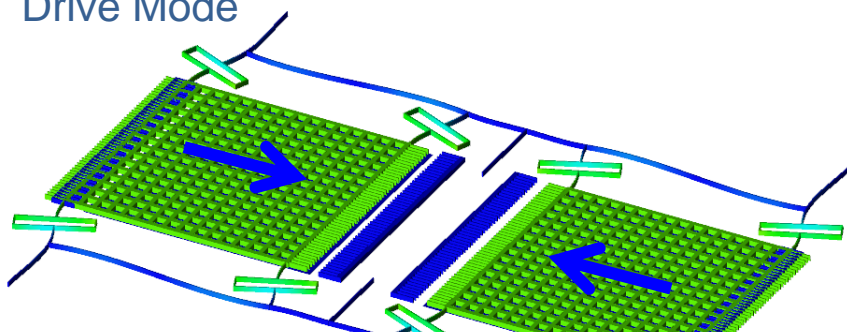
- Model Order Reduction (MOR)
- Preserves selected mechanical modes
 - Reduces from 1000s to <10 DoF
 - Preserves selected non-linear inputs

- Exported Verilog-A models
- Simulate up to 100X faster
 - Compatible with most A/MS simulators
 - Protect MEMS design IP

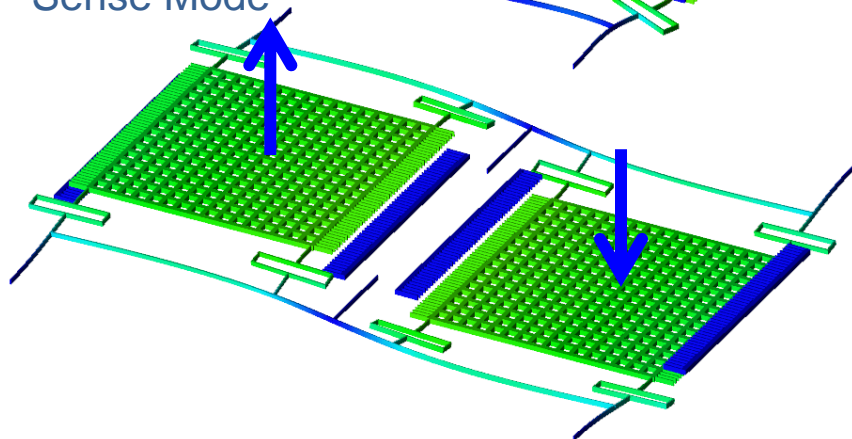
Dual-Mass Gyro Example

Key Mechanical Modes

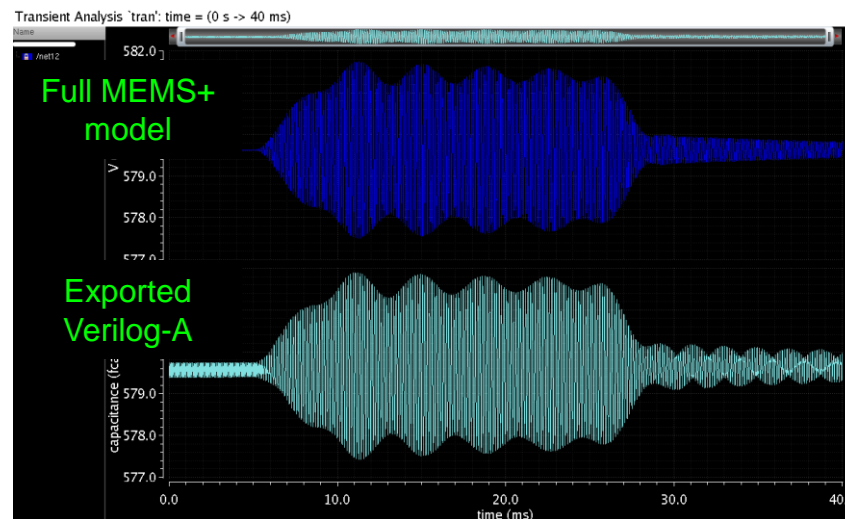
Drive Mode



Sense Mode



Transient Simulation in Cadence Spectre
response to angular acceleration pulse, 40ms real time



Verilog-A model with 2 nd -order non-linearities	Simulation time per real time (s/ms)	Speed-up vs. full MEMS+ model
Coriolis force	0.27	255X
Coriolis force and DC bias	1.15	61X

Exported Verilog-A vs. Full *MEMS+* Models

Model Characteristic	Full <i>MEMS+</i>	Exported Verilog-A
Included MEMS physics	Mechanics, electrostatics, gas damping, piezo effects, package effects	Same as full model except noise simulation
Nonlinearities	All input and state vars	Selected input vars
Parametric	Yes	No
3D Result Visualization	Yes	No
Applicable device types	Sensors (motion, mics,...), resonators, actuators	Same, except devices that depend on pull-in instability
Simulation speed	Selective simplification for speed/accuracy trade-off	Up to 100X faster
Compatible simulators	Cadence Spectre and APS	Most A/MS simulators
Protects MEMS device IP	No	Yes

Expected usage: Verilog-A models will be used for routine simulations while full *MEMS+* models will be used to investigate anomalous behavior and design corners

Applicable Device Types for Exported Verilog-A

Applicable to sensors and resonators, devices that have small displacement compared to air gap, including

- Accelerometers
- Gyros
- Microphones
- Pressure sensors
- Electrostatically-actuated resonators
- Energy harvesters
- Scanning mirrors (small motion)

Not applicable for electrostatic pull-in analysis of sensors, or actuators that depend on pull-in for intended function, including

- Switches
- Varactors (tunable capacitors)
- Digital display mirrors
- Shutters
- Scanning mirrors (large motion)

These limitations apply to MEMS+ 4.0.
Future releases will have more capabilities

Customer Quote on Exported Verilog-A

COVENTOR

Tero Sillanpää, ASIC Design Manager, Murata:

“The Verilog-A Reduced Order Model (ROM) exported from *MEMS+* 4.0 captures second order effects not seen in basic hand-crafted models without any compromise in simulation performance. We were able to create a Verilog-A ROM of a complex gyro design in just a few minutes, allowing our ASIC team to work in parallel with the MEMS team on further design iterations. Harmonic simulations in Cadence showed that the model maintained the expected modal frequencies and was stable. Moreover, transient startup simulations were very fast, on the order of 25s CPU time for 1s real time, before front-end electronic components including RC parasitic were added. The robust model exchange between MEMS and ASIC designers enabled by *MEMS+* reduces the probability of design error and can help avoid costly redesign iterations needed to address unexpected behavior.”

Exported Verilog-A models have significant advantages over hand-crafted models

“Verilog-A Export” requires a new license key

- The license key is required to export Verilog-A from *MEMS+*
- Running exported Verilog-A in Cadence or any other A/MS simulator is unlicensed.

“Verilog-A Export” is a new option on our price list

- It is an add-on to any *MEMS+* bundle
- For multi-seat quotes, the number of Verilog-A Export licenses should be the same as the number of seats
- Positive customer response indicates this is a high-value feature.

***MEMS+* models have significant benefits over traditional FEA**

- Much **faster** simulations due to reduced degrees of freedom
- **Parameterization** enables rapid design exploration and optimization
- **Compatible** with MATLAB, Simulink and Cadence simulators

***MEMS+* goes well beyond traditional FEA capabilities**

- Simulate the **dynamic** response of sensors and actuators with fully coupled physics
- Simulate closed-loop operation of sensors
- Perform noise analysis of sensors

***MEMS+* 4.0 enables a new level of MEMS+IC co-design**

- Exported Verilog-A models simulate much faster with sufficient accuracy
- Compatible with most A/MS simulators that take Verilog-A input
- Share models with partners and customers while protecting MEMS IP

감사합니다

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